		STUDY MODULE D	ESCRIPTION FORM			
Name o	f the module/subject		(Code		
Automatics and Automatic Control			1	010321231010314//3		
Field of study			Profile of study (general academic, practical) (brak)	Year /Semester		
Elective		9	Subject offered in:	Course (compulsory elective)		
LICOUVO	pairspecially	-	polish	obligatory		
Cycle of	f study:		Form of study (full-time,part-time)			
First-cycle studies			full-time			
No. of h	ours			No. of credits		
Lectur	re: 2 Classes	s: - Laboratory: 2	Project/seminars:	5		
Status o	of the course in the study	program (Basic, major, other)	(university-wide, from another field	d)		
		(brak)	(k	orak)		
Educati	on areas and fields of sci	ence and art		ECTS distribution (number and %)		
techr	nical sciences			5 100%		
	Technical scie	ences		5 100%		
Resp	onsible for subj	ect / lecturer:	Responsible for subject	/ lecturer:		
dr inż. Andrzej Kwapisz			dr inż. Jacek Handke			
ema	ail: andrzej.kwapisz@p	out.poznan.pl	email: jacek.handke@put.poznan.pl			
tei. Wvo	+48 616 652 559 Iział Elektryczny		161. +48 616 652 559 Wudział Elektryczny			
ul. F	Piotrowo 3A 60-965 Po	oznań	ul. Piotrowo 3A 60-965 Poznań			
Prere	equisites in term	s of knowledge, skills an	d social competencies:			
1	Knowledge	Has knowledge about mathematelectricity, magnetism). Has knot time and frequency domain.	tics and selected phisics sections (optisc, mechanics, wledge about signal theory and methods of it's processing in			
2	Skills	Is able to describe selected phys	sical phenomena with mathematical apparatus			
3	Social competencies	Is able to approve himself in new	v knowledge aquisition			
Assu	mptions and obj	ectives of the course:				
Getting and it's continu	g knowledge about bas parametrers adjustm uous automatic system	sic automatics components, auton ent for different types of regulatior ns with application of different ana	natic system and regulation, known objects. Knowledge about synth lytic methods and numerical moc	vledge of regulator selection nesis methods and analysis of leling.		
	Study outco	mes and reference to the	educational results for a	i field of study		
Knov	vledge:					
1. Has	general konwledge al	pout use and operation of automat	tic systems [K_W01 +++]			
2. Understands the principles and methods of mathematical modeling and practical application of automatic control systems - [K W14 +++]						
Skills	5:					
1. Is at [K_U0′	ble to identify basic au 1 +++]	tomatic components and automat	ic control systems on the basis o	f its specific features		
2. s able to use software tools for research of automatic system features and it - [K_U09 +++]						
3. Is able to design and evaluate the results of a simple automatic control system operation - [K_U13 +++]						
Social competencies:						
1. Is aware of the significant impact of engineering and automatic control systems on the environment - [K_K02 ++]						
2. Und	erstands the need for	continuous professional developm	nent, personal and group coopera	ation - [K_K03 ++]		
		Accoment wether				

Assessment methods of study outcomes

Faculty of Electrical Engineering				
Lecture				
evaluation of the knowledge and skills on the basis of written tests.				
classroom activity rewarding.				
Laboratory:				
tests and written tests.				
evaluation of knowledge and skills related to the accomplishment practice task				
evaluation of report from performed exercise				
Obtainment of extra points for the activity in the classroom, in particular for:				
effectiveness of the application of acquired knowledge during studies.				
ability to work within a team performing the detailed practice task in the laboratory				
contribution to the achievement of the tasks.				
Course description				
Basic concepts of control theory, the division of control systems. Mathematical description of linear con and spectral function, examples. Description of the control system state variables. Properties of the bas automation. Time and frequency characterisctis. Block diagrams of automatic control systems, flowcha Properties of regulators, tuning and examples. The stability of continuous linear systems, the general c algebraic and graphical criteria. Correction in control systems. Linear discrete systems, system stability (static characteristics, dynamics analysis methods, examples). Quality of control, static accuracy, desci of dynamic systems.	trol systems, transfer sic elements of rt conversion. onditions of stability, v. Nonlinear systems ription of the properties			
Basic bibliography:				
1. Baron K. Latarnik M. Skrzywan-Kosek A. Świerniak A.: Zbiór zadań z teorii liniowych układów regula 1999	icji, Wydanie IV, WPŚ			
2. Dębowski A., Automatyka - Podstawy teorii, WNT 2008				
3. Rumatowski K., Podstawy automatyki. Część 1. Układy liniowe o działaniu ciągłym, WPP 2004				
4. Rumatowski K., Podstawy regulacji automatycznej, WPP 2008				
5. Zabczyk J., Zarys matematycznej teorii sterowania, PWN 1991				
Additional bibliography:				
1. Horla D., Podstawy automatyki. Ćwiczenia laboratoryjne, wyd. 3, poprawione i uzupełnione, Poznań Politechniki Poznańskiej 2009	, Wydawnictwo			
2. Manitoba HVDC Research Centre: PSCAD? Users Guide V4.3., 2010				
3. Mrozek B. Mrozek Z., Matlab i Simulink. Poradnik użytkownika. Wydanie II, HELION 2004				
4. Pincon B., Wprowadzenie do Scilaba, Institut Elie Cartan Nancy F S I A L. Université Henri Poincaré, 2009				
Result of average student's workload				
Activity	Time (working hours)			
1. participation in class lectures	30			
2. participation in laboratory classes	30			
3. participate in the consultations on the lecture	5			
4. participate in the consultations on the laboratory	5			
5. preparation laboratory reports	20			
6. preparartion to the laboratory classes	7			
7. preparation of home work	7			
8. prepare for the completion of laboratory	4			
9. completion of laboratory classes	2			
10. prepare for the completion of class lectures	5			
11. completion of class lectures	4			
12. student's selfmanaged work	20			
Student's workload				

Source of workload	hours	ECTS
Total workload	137	5
Contact hours	74	3
Practical activities	95	2